

The Cramér-Rao Bound and Its Application to Quantification in MRS

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Abstract

Cramer-Rao Bound (CRB) is an important inequality on the error correlation matrix of an estimator. It describes the theoretical lower bound for an estimator (usually unbiased). Therefore, it is a useful index of how efficiently an estimator is. Here we will summarize the derivation of CRB, list some examples and apply this analysis to the quantification (parameters estimation) of spin-echo signals in MRI.

I. CRAMER-RAO BOUND

This section and the following examples section are essentially based on Levy's book *Principles of signal detection and parameter estimation* [1].

A. Definition

Let the parameters of an estimator be an m dimensional vector x , and the measurement data be an n dimensional vector Y . The estimator here is denoted by $\hat{X}(Y)$. The Cramer-Rao Bound that we usually used for unbiased estimators is

$$C_E(x) \geq J^{-1}(x), \quad (1)$$

where

$$C_E(x) = E[(x - \hat{X}(Y))(x - \hat{X}(Y))^T] \quad (2)$$

is the error correlation matrix of X , and

$$J(x) = E_Y[\nabla_x \ln f_Y(Y|x)(\nabla_x \ln f_Y(Y|x))^T], \quad (3)$$

or equivalently (which is proved in [1]),

$$J(x) = -E_Y[\nabla_x \nabla_x^T \ln f_Y(Y|x)], \quad (4)$$

is the so-called Fisher Information in Y about the parameters in X . Note in (3) and (4), $f_Y(Y|X)$ is the conditional probability distribution function of measurement Y on parameters X , and the gradient operator is defined as

$$\nabla_x = \left[\frac{\partial}{\partial x_1} \quad \frac{\partial}{\partial x_2} \quad \cdots \quad \frac{\partial}{\partial x_m} \right]^T. \quad (5)$$

In practice, the Fisher Information can be calculated entry-wisely in the following two ways.

$$\begin{aligned} J_{i,j}(x) &= E_Y \left[\frac{\partial}{\partial x_i} \ln f_Y(Y|x) \frac{\partial}{\partial x_j} \ln f_Y(Y|x) \right] \\ &= -E_Y \left[\frac{\partial^2}{\partial x_i \partial x_j} \ln f_Y(Y|x) \right]. \end{aligned} \quad (6)$$

Given this bound, we have the estimator variance of each parameter,

$$E[(x_i - \hat{x}_i(Y))^2] \geq [J^{-1}]_{ii}(x), \quad (7)$$

which is useful in the analysis of the efficiency of an estimator.

B. Proof

We prove a more generalized form:

$$C_E(x) \geq b(x)b^T(x) + (I_m - \nabla_X^T b(x))J^{-1}(x)(I_m - \nabla_X^T b(x))^T, \quad (8)$$

where $b(x)$ is the bias of this estimator,

$$b(x) = x - E(\hat{X}(Y)). \quad (9)$$

It is obvious that when the estimator is unbiased, that is, $b(x) = 0$, (8) degenerates to (1).

Form a $2m$ dimensional vector

$$Z = \begin{bmatrix} x - \hat{X}(Y) - b(x) \\ \nabla_x \ln(f_Y(Y|x)) \end{bmatrix}. \quad (10)$$

Then let

$$C_Z = E[ZZ^T] = \begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix} \quad (11)$$

be its correlation matrix. From (2) and (3), we can immediately have

$$C_{11} = C_E(x) - b(x)b^T(x), \quad (12)$$

$$C_{22} = J(x). \quad (13)$$

It remains to evaluate

$$\begin{aligned} C_{21}^T &= C_{12} = E[(x - \hat{X}(Y) - b(x)) \nabla_X^T \ln(f_Y(Y|x))] \\ &= \int (x - \hat{X}(y) - b(x)) \nabla_x^T (f_Y(y|x)) dy. \end{aligned} \quad (14)$$

Note

$$\begin{aligned} 0 &= \nabla_x^T \{ [x - \hat{X}(y) - b(x)] f_Y(y|x) \} \\ &= f_Y(y|x) \nabla_x^T [x - \hat{X}(y) - b(x)] + [x - \hat{X}(y) - b(x)] \nabla_x^T f_Y(y|x) \\ &= f_Y(y|x) [I_m - \nabla_x^T b(x)] + [x - \hat{X}(y) - b(x)] \nabla_x^T f_Y(y|x). \end{aligned} \quad (15)$$

Integrating this identity with respect to y gives

$$C_{12} = -I_m + \nabla_x^T b(x). \quad (16)$$

Assuming the information matrix $C_{22} = J(x)$ is positive definite (i.e., invertible, which is usually true) at point X , we can perform Schur decomposition to $C_Z(x)$:

$$\begin{pmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{pmatrix} = \begin{pmatrix} I_m & C_{12}C_{22}^{-1} \\ 0 & I_m \end{pmatrix} \begin{pmatrix} C_{11} - C_{12}C_{22}^{-1}C_{21} & 0 \\ 0 & C_{22} \end{pmatrix} \begin{pmatrix} I_m & 0 \\ C_{22}^{-1}C_{21} & I_m \end{pmatrix}.$$

Because the correlation matrix $C_Z(x) \geq 0$, $C_{11} - C_{12}C_{22}^{-1}C_{21}$ is also non-negative definite, i.e.,

$$C_E(x) - b(x)b^T(x) - (I_m - \nabla_x^T b(x))J^{-1}(x)(I_m - \nabla_x^T b(x))^T \geq 0, \quad (17)$$

which is exactly (8).

□

C. Example

1) *CRB Calculation:* Consider the estimation of the mean and variance of a sequence $\{Y_k, 1 \leq k \leq N\}$ of i.i.d. $N(m, v)$ gaussian random variables.

$$f_Y(y_k|m, v) = \frac{1}{\sqrt{2\pi v}} e^{-\frac{(y_k-m)^2}{2v}}, k = 1, 2, \dots, N,$$

$$f_Y(\mathbf{y}|m, v) = \frac{1}{(\sqrt{2\pi v})^N} e^{-\frac{\sum_{k=1}^N (y_k-m)^2}{2v}},$$

$$L(\mathbf{y}|m, v) = \ln(f_Y(\mathbf{y}|m, v)) = -\frac{N}{2} \ln(2\pi v) - \frac{1}{2v} \sum_{k=1}^N (y_k - m)^2.$$

First order derivatives are

$$\frac{\partial L}{\partial m} = \frac{1}{v} \sum_{k=1}^N (y_k - m), \quad (18)$$

and

$$\frac{\partial L}{\partial v} = -\frac{N}{2v} + \frac{1}{2v^2} \sum_{k=1}^N (y_k - m)^2. \quad (19)$$

Then second derivatives are

$$\frac{\partial^2 L}{\partial m^2} = -\frac{N}{v},$$

$$\frac{\partial^2 L}{\partial v^2} = \frac{N}{2v^2} - \frac{1}{v^3} \sum_{k=1}^N (y_k - m)^2,$$

and

$$\frac{\partial^2 L}{\partial m \partial v} = -\frac{1}{v^2} \sum_{k=1}^N (y_k - m).$$

Therefore the Fisher Information matrix is

$$J(m, v) = N \begin{pmatrix} v^{-1} & 0 \\ 0 & (2v^2)^{-1} \end{pmatrix}, \quad (20)$$

$$J^{-1}(m, v) = N^{-1} \begin{pmatrix} v & 0 \\ 0 & 2v^2 \end{pmatrix}. \quad (21)$$

Then the error variances of the entries of any unbiased estimator must satisfy

$$E[(m - \hat{m}(Y))^2] \geq \frac{v}{N}, \quad (22)$$

$$E[(v - \hat{v}(Y))^2] \geq \frac{2v^2}{N}. \quad (23)$$

2) *Efficiency*: An unbiased estimator is efficient if it reaches its CRB, which means $C_E(X) - J^{-1}(X) = 0$. Further if only a partial of the eigenvalues of $C_E(X) - J^{-1}(X)$ is zero, it is called partially efficient.

By setting (18) and (19) to be zero, we have

$$\hat{m}_{ML}(Y) = \frac{1}{N} \sum_{k=1}^N y_k, \quad (24)$$

and

$$\hat{v}_{ML}(Y) = \frac{1}{N} \sum_{k=1}^N (y_k - \hat{m})^2. \quad (25)$$

It is proved in [1] that

$$E[\hat{m}_{ML}(Y)] = m, \quad (26)$$

$$E[\hat{v}_{ML}(Y)] = \frac{N-1}{N}v, \quad (27)$$

$$E[(m - \hat{m}_{ML}(Y))^2] = \frac{v}{N}, \quad (28)$$

$$E[(v - \hat{v}_{ML}(Y))^2] = \frac{2N-1}{N^2}v^2. \quad (29)$$

From the results we see that the unbiased estimator $\hat{m}_{ML}(Y)$ is efficient because it reaches its CRB as defined in (21). Even though the estimator $\hat{v}_{ML}(Y)$ is biased, its error variance, however, is smaller than the CRB for unbiased estimators. This implies that it is not necessary that biased estimators have poor error variance performances, instead allowing a small bias can sometimes be beneficial.

Another fact mentioned in [1] on pp. 145 is that all ML estimators have these two properties:

- 1) Asymptotically unbiased, i.e., $\lim_{N \rightarrow \infty} b(X) = 0$;
- 2) Asymptotically efficient, i.e., $\lim_{N \rightarrow \infty} E[(x_i - \hat{x}_i(Y))^2] = [J^{-1}]_{ii}(X)$;

which can be seen from the example above.

II. QUANTIFICATION OF SINGLE SPIN-ECHO SIGNALS

A. Formulation

We use the model that introduced in Chap. 5.2 *Proposed formulation* [2], ignoring baseline signals.

$$s[m] = s_{metab}[m] + \xi[m], \quad (30)$$

$$s_{metab}[m] = e^{i\phi_0} \sum_{n=1}^N a_n(TE) \varphi_{n,TE}[m] \psi_{n,d_n}[m], \quad (31)$$

$$m = 0, 1, \dots, M-1,$$

where $\xi[m] \sim N(0, \sigma^2)$ is a complex gaussian noise, ϕ_0 is a zero-order term phase, $a_n(TE)$ is a real positive amplitude assumed to exponentially decay with respect to TE

$$a_n(TE) = c_n e^{-TE/T_{2,n}}, \quad (32)$$

and $\varphi_{n,TE}[m]$ and $\psi_{n,d_n}[m]$ are metabolite basis function and signal decay, respectively, defined as

$$\varphi_{n,TE}[m] = \sum_{l=1}^{L_n} \alpha_{l,n}(TE) e^{-i\beta_{l,n}(TE)} e^{-i2\pi f_{l,n}(TE)m\Delta t}, \quad (33)$$

$$\psi_{n,d_n}[m] = e^{-m\Delta t/d_n}. \quad (34)$$

In the above formulations, $T_{2,n}$ is a metabolite-dependent relaxation constant, d_n is a real lineshape parameter and Δt is the sampling time. $\alpha_{l,n}(TE)$, $\beta_{l,n}(TE)$ and $f_{l,n}(TE)$ are relative amplitude, phase and frequency of the l -th resonance of the n -th metabolite which can all be determined from quantum mechanical simulations.

The parameter vector that we are going to estimate is

$$\theta = [a_1, \dots, a_N, d_1, \dots, d_N, \phi_0]^T. \quad (35)$$

B. Entrywise Derivation of CRB

The probability distribution function of an n -channel i.i.d. real gaussian variable $X \sim N(0, \sigma^2 I_n)$, $X \in \mathbb{C}^n$ is

$$f_X(x) = \frac{1}{(2\pi\sigma^2)^{n/2}} e^{-\frac{\|x\|^2}{2\sigma^2}}. \quad (36)$$

The likelihood function of $s[m]$, $m = 0, \dots, M-1$ is therefore

$$L(s[m]) = \frac{1}{(\pi\sigma^2)^M} e^{-\frac{|\xi[m]|^2}{\sigma^2}},$$

$$\ln L(s[m]) = \text{const} - \frac{1}{\sigma^2} \sum_{m=0}^{M-1} |\xi[m]|^2, \quad (37)$$

where $\xi[m] \sim N(0, \sigma^2)$. Using the result that $\frac{\partial \|z\|^2}{\partial \alpha} = z(\frac{\partial z^*}{\partial \alpha}) + z^*(\frac{\partial z}{\partial \alpha}) = 2\text{Re}\{z(\frac{\partial z^*}{\partial \alpha})\}$ where $z \in \mathbb{C}$, $\alpha \in \mathbb{R}$, we have

$$\frac{\partial \ln L}{\partial \theta_k} = -\frac{1}{\sigma^2} \sum_{m=0}^{M-1} \left\{ \xi[m] \frac{\partial \xi^*[m]}{\partial \theta_k} + \xi^*[m] \frac{\partial \xi[m]}{\partial \theta_k} \right\}, \quad (38)$$

where

$$\xi^*[m] = s^*[m] - e^{-i\phi_0} \sum_{n=1}^N a_n(TE) \varphi_{n,TE}^*[m] \psi_{n,d_n}^*[m],$$

$$\left(\frac{\partial \xi[m]}{\partial a_k}\right)^* = \frac{\partial \xi^*[m]}{\partial a_k} = -e^{-i\phi_0} \varphi_{k,TE}^*[m] \psi_{k,d_k}^*[m], \quad (39)$$

$$\left(\frac{\partial \xi[m]}{\partial d_k}\right)^* = \frac{\partial \xi^*[m]}{\partial d_k} = -e^{-i\phi_0} a_k(TE) \varphi_{k,TE}^*[m] \frac{\partial \psi_{k,d_k}^*[m]}{\partial d_k}, \quad (40)$$

$$\left(\frac{\partial \xi[m]}{\partial \phi_0}\right)^* = \frac{\partial \xi^*[m]}{\partial \phi_0} = ie^{-i\phi_0} \sum_{n=1}^N a_n(TE) \varphi_{n,TE}^*[m] \psi_{n,d_n}^*[m], \quad (41)$$

$$k = 1, 2, \dots, N.$$

By (6), we have

$$F_{p,q}(\theta) = E_\xi \left[\left(\frac{\partial \ln L}{\partial \theta_p} \right) \left(\frac{\partial \ln L}{\partial \theta_q} \right) \right] \quad (42)$$

In calculating that, we will need the expectation of $\xi^*[m_1]\xi[m_2]$ and $\xi[m_1]\xi[m_2]$, $\forall m_1, m_2 = 1, \dots, M$. Because the gaussian noise channels are i.i.d., it is easy to get

$$E_\xi \{ \xi^*[m_1] \xi[m_2] \} = \begin{cases} \sigma^2, & \text{for } m_1 = m_2 \\ 0, & \text{for } m_1 \neq m_2 \end{cases} \quad (43)$$

$$E_\xi \{ \xi[m_1] \xi[m_2] \} = 0, \text{ for } m_1 \neq m_2.$$

To handle $\xi[m]\xi[m]$, we firstly decompose it into real variables:

$$\xi[m] = \xi_r[m] + i\xi_i[m], \quad (44)$$

where $\xi_r[m], \xi_i[m] \sim N(0, \frac{\sigma^2}{2})$ and are independent with each other. And then

$$E_\xi \{ \xi[m] \xi[m] \} = E_\xi \{ \xi_r^2 + 2i\xi_r\xi_i - \xi_i^2 \} = E_\xi \{ \xi_r^2 - \xi_i^2 \} = 0. \quad (45)$$

Therefore

$$E_\xi \{ \xi[m_1] \xi[m_2] \} = 0, \forall m_1, m_2 = 1, \dots, M. \quad (46)$$

Taking (43) and (46) into consideration, the entries of the Fisher Information matrix is

$$\begin{aligned}
F_{p,q}(\theta) &= \frac{1}{\sigma^4} E_\xi \left\{ \sum_{m_1=0}^{M-1} \left[\xi[m_1] \frac{\partial \xi^*[m_1]}{\partial \theta_p} + \xi^*[m_1] \frac{\partial \xi[m_1]}{\partial \theta_p} \right] \right. \\
&\quad \left. \sum_{m_2=0}^{M-1} \left[\xi[m_2] \frac{\partial \xi^*[m_2]}{\partial \theta_q} + \xi^*[m_2] \frac{\partial \xi[m_2]}{\partial \theta_q} \right] \right\} \\
&= \frac{1}{\sigma^4} E_\xi \left\{ \sum_{m=0}^{M-1} \left[\xi[m] \xi^*[m] \frac{\partial \xi^*[m]}{\partial \theta_p} \frac{\partial \xi[m]}{\partial \theta_q} + \xi^*[m] \xi[m] \frac{\partial \xi[m]}{\partial \theta_p} \frac{\partial \xi^*[m]}{\partial \theta_q} \right] \right\} \\
&= \frac{1}{\sigma^2} \sum_{m=0}^{M-1} \left[\frac{\partial \xi^*[m]}{\partial \theta_p} \frac{\partial \xi[m]}{\partial \theta_q} + \frac{\partial \xi[m]}{\partial \theta_p} \frac{\partial \xi^*[m]}{\partial \theta_q} \right] \\
&= \frac{2}{\sigma^2} \sum_{m=0}^{M-1} \operatorname{Re} \left\{ \frac{\partial \xi^*[m]}{\partial \theta_p} \frac{\partial \xi[m]}{\partial \theta_q} \right\}. \tag{47}
\end{aligned}$$

$$\tag{48}$$

Substituting (39)(40)(41) into (47), we get for $\forall p, q = 1, \dots, N$

$$\begin{aligned}
F_{a_p, a_q}(\theta) &= \frac{2}{\sigma^2} \sum_{m=0}^{M-1} \operatorname{Re} \left\{ \frac{\partial \xi^*[m]}{\partial a_p} \frac{\partial \xi[m]}{\partial a_q} \right\} \\
&= \frac{2}{\sigma^2} \sum_{m=0}^{M-1} \operatorname{Re} \left\{ -e^{-i\phi_0} \varphi_{p,TE}^*[m] \psi_{p,d_p}^*[m] (-e^{i\phi_0} \varphi_{q,TE}[m] \psi_{q,d_q}[m]) \right\} \\
&= \frac{2}{\sigma^2} \sum_{m=0}^{M-1} \operatorname{Re} \left\{ \varphi_{p,TE}^*[m] \psi_{p,d_p}^*[m] \varphi_{q,TE}[m] \psi_{q,d_q}[m] \right\}, \tag{49}
\end{aligned}$$

$$\begin{aligned}
F_{d_p, d_q}(\theta) &= \frac{2}{\sigma^2} \sum_{m=0}^{M-1} \operatorname{Re} \left\{ \frac{\partial \xi^*[m]}{\partial d_p} \frac{\partial \xi[m]}{\partial d_q} \right\} \\
&= \frac{2}{\sigma^2} \sum_{m=0}^{M-1} \operatorname{Re} \left\{ a_p a_q \varphi_{p,TE}^*[m] \frac{\partial \psi_{p,d_p}^*[m]}{\partial d_p} \varphi_{q,TE}[m] \frac{\partial \psi_{q,d_q}[m]}{\partial d_q} \right\}, \tag{50}
\end{aligned}$$

$$\begin{aligned}
F_{\phi_0, \phi_0}(\theta) &= \frac{2}{\sigma^2} \sum_{m=0}^{M-1} \operatorname{Re} \left\{ \frac{\partial \xi^*[m]}{\partial \phi_0} \frac{\partial \xi[m]}{\partial \phi_0} \right\} \\
&= \frac{2}{\sigma^2} \sum_{m=0}^{M-1} \operatorname{Re} \left\{ \sum_{n_1=1}^N a_{n_1} \varphi_{n_1,TE}^*[m] \psi_{n_1, d_{n_1}}^*[m] \right. \\
&\quad \left. \sum_{n_2=1}^N a_{n_2} \varphi_{n_2,TE}[m] \psi_{n_2, d_{n_2}}[m] \right\}
\end{aligned}$$

$$= \frac{2}{\sigma^2} \sum_{m=0}^{M-1} \operatorname{Re} \left\{ \sum_{n_1=1}^N \sum_{n_2=1}^N a_{n_1} a_{n_2} \varphi_{n_1,TE}^*[m] \psi_{n_1,d_{n_1}}^*[m] \varphi_{n_2,TE}[m] \psi_{n_2,d_{n_2}}[m] \right\}, \quad (51)$$

$$\begin{aligned} F_{a_p,d_q}(\theta) &= \frac{2}{\sigma^2} \sum_{m=0}^{M-1} \operatorname{Re} \left\{ \frac{\partial \xi^*[m]}{\partial a_p} \frac{\partial \xi[m]}{\partial d_q} \right\} \\ &= \frac{2}{\sigma^2} \sum_{m=0}^{M-1} \operatorname{Re} \left\{ a_q \varphi_{p,TE}^*[m] \psi_{p,d_p}^*[m] \varphi_{q,TE}[m] \frac{\partial \psi_{q,d_q}[m]}{\partial d_q} \right\}, \end{aligned} \quad (52)$$

$$\begin{aligned} F_{a_p,\phi_0}(\theta) &= \frac{2}{\sigma^2} \sum_{m=0}^{M-1} \operatorname{Re} \left\{ \frac{\partial \xi^*[m]}{\partial a_p} \frac{\partial \xi[m]}{\partial \phi_0} \right\} \\ &= \frac{2}{\sigma^2} \sum_{m=0}^{M-1} \operatorname{Re} \left\{ i \varphi_{p,TE}^*[m] \psi_{p,d_p}^*[m] \sum_{n=1}^N a_n \varphi_{n,TE}[m] \psi_{n,d_n}[m] \right\} \\ &= -\frac{2}{\sigma^2} \sum_{m=0}^{M-1} \operatorname{Im} \left\{ \varphi_{p,TE}^*[m] \psi_{p,d_p}^*[m] \sum_{n=1}^N a_n \varphi_{n,TE}[m] \psi_{n,d_n}[m] \right\}, \end{aligned} \quad (53)$$

$$\begin{aligned} F_{d_p,\phi_0}(\theta) &= \frac{2}{\sigma^2} \sum_{m=0}^{M-1} \operatorname{Re} \left\{ \frac{\partial \xi^*[m]}{\partial d_p} \frac{\partial \xi[m]}{\partial \phi_0} \right\} \\ &= \frac{2}{\sigma^2} \sum_{m=0}^{M-1} \operatorname{Re} \left\{ i a_p \varphi_{p,TE}^*[m] \frac{\partial \psi_{p,d_p}^*[m]}{\partial d_p} \sum_{n=1}^N a_n \varphi_{n,TE}[m] \psi_{n,d_n}[m] \right\} \\ &= -\frac{2}{\sigma^2} \sum_{m=0}^{M-1} \operatorname{Im} \left\{ a_p \varphi_{p,TE}^*[m] \frac{\partial \psi_{p,d_p}^*[m]}{\partial d_p} \sum_{n=1}^N a_n \varphi_{n,TE}[m] \psi_{n,d_n}[m] \right\}. \end{aligned} \quad (54)$$

Here we have got the entries of $F_{p,q}(\theta)$ above its diagonal, and the rest of the entries are the conjugate transpose of the upper triangular part.

$$F(\theta) = \begin{pmatrix} F_{a,a} & F_{a,d} & F_{a,\phi_0} \\ F_{a,d}^H & F_{d,d} & F_{d,\phi_0} \\ F_{a,\phi_0}^H & F_{d,\phi_0}^H & F_{\phi_0,\phi_0} \end{pmatrix}. \quad (55)$$

C. Matrix Derivation of CRB

In deriving the CRB entrywisely, we see the formulations are much complicated due to a large number of summations. If we utilize matrix derivatives, the labor can be greatly reduced.

Rewrite the signal model in matrix form.

$$\mathbf{s} = e^{i\phi_0} \mathbf{Z} \mathbf{a} + \xi, \quad (56)$$

where $\mathbf{Z}_{m,n} = \varphi_{n,TE}[m]\psi_{d,d_n}[m]$, $m = 0, \dots, M-1$, $n = 1, \dots, N$ and

$$\mathbf{s} = \begin{pmatrix} s[0] \\ s[1] \\ \vdots \\ s[M-1] \end{pmatrix}, \mathbf{a} = \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_N \end{pmatrix}, \mathbf{d} = \begin{pmatrix} d_1 \\ d_2 \\ \vdots \\ d_N \end{pmatrix}, \xi = \begin{pmatrix} \xi[0] \\ \xi[1] \\ \vdots \\ \xi[M-1] \end{pmatrix}. \quad (57)$$

I will not keep these variables bold face hereafter for simplicity. Then the likelihood function is

$$\ln L(s) = \text{const} - \frac{1}{\sigma^2} \|\xi\|^2. \quad (58)$$

According to my previous weekly summary (week 12) of the gradient calculation of least squares problems, we have

$$\nabla_{\theta} \ln L = -\frac{1}{\sigma^2} (J^H \xi + (J^H \xi)^*), \quad (59)$$

where J is the jacobian matrix of ξ over θ (denote the Fisher Information matrix by another notation F to avoid conflict).

$$\begin{aligned} J &= \frac{\partial \xi}{\partial \theta} \\ &= \begin{bmatrix} \frac{\partial \xi}{\partial a} & \frac{\partial \xi}{\partial d} & \frac{\partial \xi}{\partial \phi_0} \end{bmatrix} \\ &= \begin{bmatrix} -e^{i\phi_0} Z & -e^{i\phi_0} D A & -ie^{i\phi_0} Z a \end{bmatrix}, \end{aligned} \quad (60)$$

where

$$D = \begin{bmatrix} \frac{\partial Z_1}{\partial d_1} & \dots & \frac{\partial Z_N}{\partial d_N} \end{bmatrix}, \quad (61)$$

$$A = \begin{pmatrix} a_1 & 0 & \dots & 0 \\ 0 & a_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & a_N \end{pmatrix}. \quad (62)$$

By (3) and (59), we have

$$\begin{aligned} F &= E \left\{ (\nabla_{\theta} \ln L) (\nabla_{\theta} \ln L)^H \right\} \\ &= \frac{1}{\sigma^4} E \left\{ (J^H \xi + (J^H \xi)^*) (\xi^H J + (\xi^H J)^*) \right\} \\ &= \frac{2}{\sigma^2} \text{Re} \{ J^H J \}. \end{aligned} \quad (63)$$

Using (60), we have

$$F_{a,a}(\theta) = \frac{2}{\sigma^2} \text{Re}\{Z^H Z\}, \quad (64)$$

$$F_{d,d}(\theta) = \frac{2}{\sigma^2} \text{Re}\{A^H D^H D A\}, \quad (65)$$

$$F_{\phi_0,\phi_0}(\theta) = \frac{2}{\sigma^2} \text{Re}\{a^H Z^H Z a\}, \quad (66)$$

$$F_{a,d}(\theta) = \frac{2}{\sigma^2} \text{Re}\{Z^H D A\}, \quad (67)$$

$$F_{a,\phi_0}(\theta) = -\frac{2}{\sigma^2} \text{Im}\{Z^H Z a\}, \quad (68)$$

$$F_{d,\phi_0}(\theta) = -\frac{2}{\sigma^2} \text{Im}\{A^H D^H Z a\}. \quad (69)$$

Finally

$$F(\theta) = \begin{pmatrix} F_{a,a} & F_{a,d} & F_{a,\phi_0} \\ F_{a,d}^H & F_{d,d} & F_{d,\phi_0} \\ F_{a,\phi_0}^H & F_{d,\phi_0}^H & F_{\phi_0,\phi_0} \end{pmatrix}. \quad (70)$$

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